

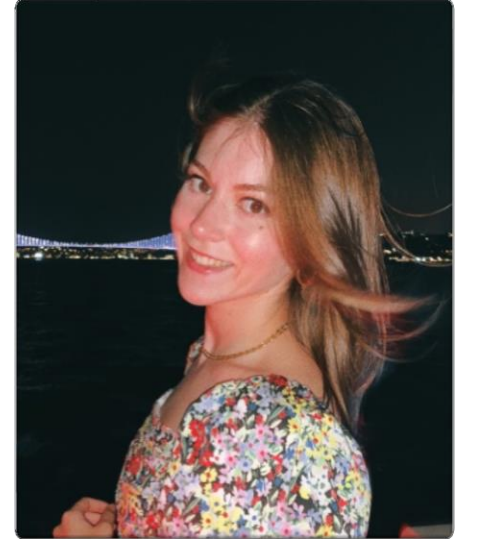
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SIGMA TEAM

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System

Linearization

MPC

Integral action

Input
constraint

Quadratic
Programming

